

Introduction to the Design of Space Mechanisms

Theme 4:
Materials
Part 1

Gilles Feusier



© SpaceX



© Thales Alenia Space

Material Properties

- Fundamental properties
 - Physical
 - Mechanical
 - Thermal
 - Electrical
 - Magnetic
 - Optical
- Necessary Verifications and Qualifications
 - ECSS-Q-ST-70C Rev.2 [4.1]
Space Product Assurance - Materials, mechanical parts and processes
- Selection
 - ECSS-Q-ST-70-71C Rev.1 [4.2]
Space Product Assurance - Materials, processes and their data selection
 - Note: European Space Materials Database (ESMDB) available at ESA.

Material Properties

- Physical properties
 - Specific weight
 - Metallurgical states
 - Highly dependent on the phase
 - Strength, elasticity, toughness, resilience, wear, ...
 - Magnetic susceptibility, remanent magnetization
 - Heat capacity, linear thermal expansion, melting, vaporization
 - Chemical
 - Outgassing
 - Vapor pressure
 - Absorption, adsorption
 - Electrochemical potential
 - Corrosion, stress-corrosion cracking
 - Aging
 - Biocompatibility, toxicity
 - Flammability
 - Environmental
 - Resistance against radiations
 - Water absorption
 - Resistance to biological agents (fungus, bacteria, ...)

Mechanical Properties

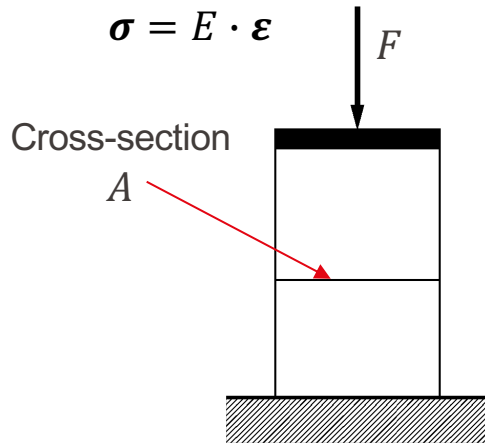
- Strength (tensile, bending, compression)
 - Ultimate Tensile Strength (UTS) [MPa]
 - Yield Strength (Hooke's law) [MPa]
- Fatigue strength
 - Cyclic loading
 - Crack growth related to the number of cycles, until fracture
- Shock Resistance (toughness)
 - Energy of mechanical deformation to fracture
 - Effects of notches
 - Dynamic effects (impact)
- Wear resistance
 - Hertz pressure
 - Materials in contact
- Other properties
 - Hardness, ductility, creep, friction coefficient

Mechanical Properties (reminder)

- Stress (σ), strain (ε), stiffness (k), Hooke's law, Young's modulus (E)

$$\sigma = \frac{F}{A} \quad \varepsilon = \frac{\Delta L}{L}$$

$$\sigma = E \cdot \varepsilon$$

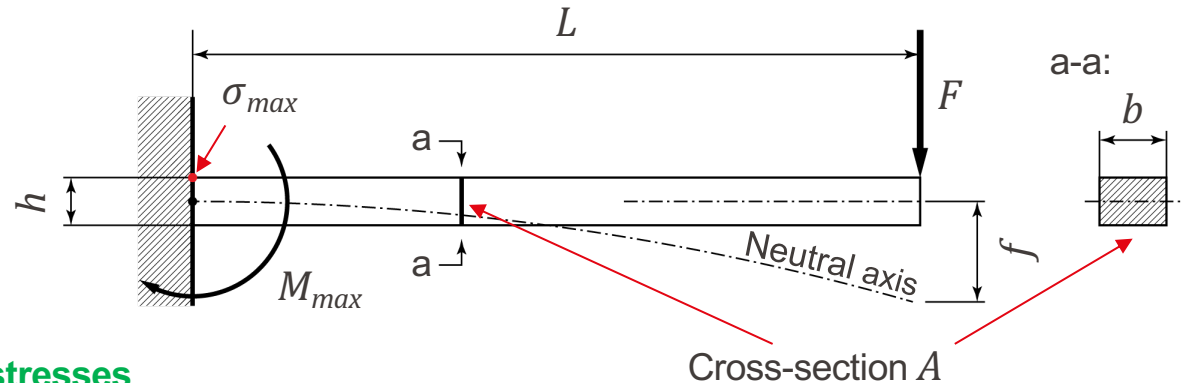


Example: **cantilever beam**, rectangular cross-section

Stiffness: $k = \frac{F}{f}$ Deflection: $f = \frac{F \cdot L^3}{3 \cdot E \cdot I}$ with $I = \frac{b \cdot h^3}{12}$

I : area moment of inertia (second moment of area)

Maximum stress: $\sigma_{max} = \frac{M_{max}}{2 \cdot I} h$

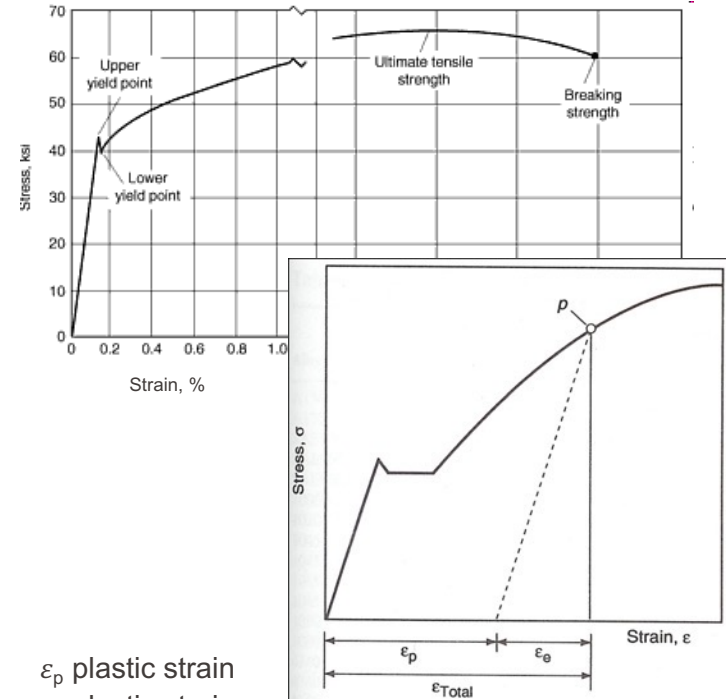
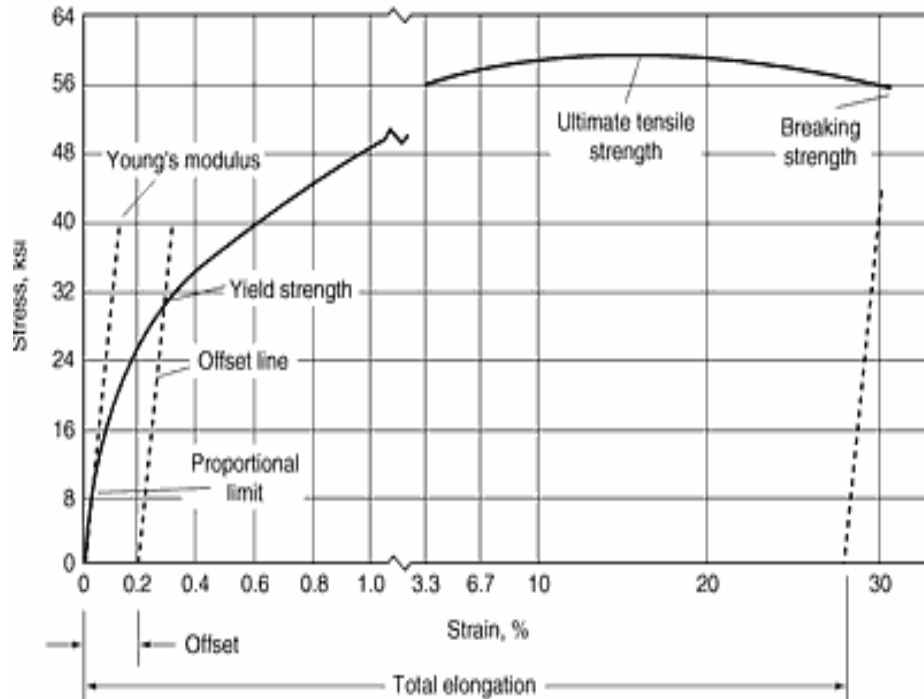


Exercise 4.1: Solar Array

Exercise 4.2: Stiffness and stresses

■ Tensile test

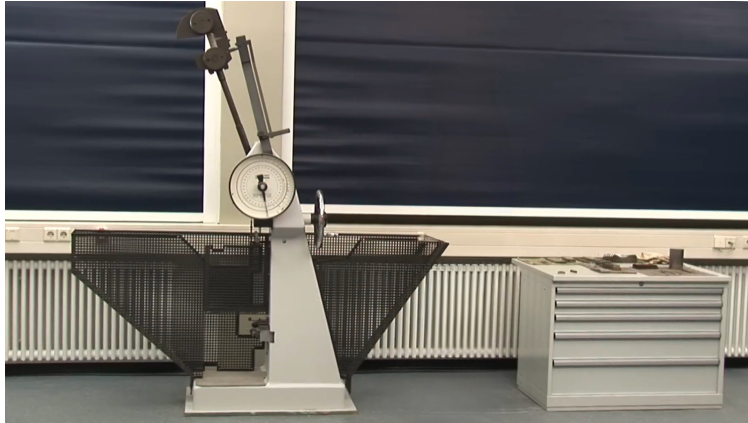
- Stress-Strain curve (source: ASM Metals Handbook)



■ Toughness

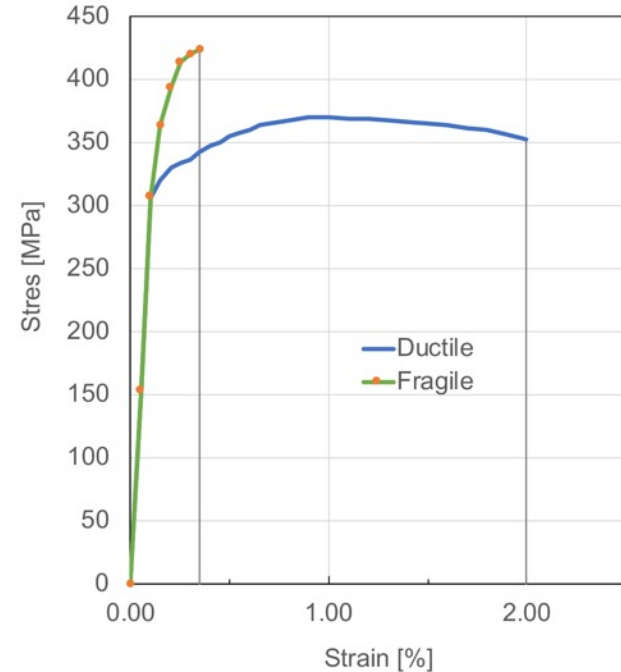
- Ability to absorb energy before fracture

Impact Pendulum (Charpy Test)



Source: MaterialsScience2000/Youtube

Unit (SI): J/m³



ECSS-Q-ST-70-71C Rev.1

4.2.21 Ceramics and other non-metallic materials

“Ceramics and glasses, except as fibres, shall not be used in a structural applications without the prior approval of the customer.”

What is the main cause of brittle fracture?

- Turn out to your neighbors (3-5 people teams)
- What is the main cause of brittle fractures?
- Do you have some examples, examples of failures? From your own experience?
- 5 minutes discussion
- Share your outcomes

■ Fatigue

- Weakening caused by cyclic loads
 - Applied forces of variable amplitudes (oscillatory, unidirectional periodic, random, vibrations, ...)
 - Thermal cycles
- The fatigue depends on:
 - The material
 - Ductility, brittleness
 - Strength, intergranular cohesion, inclusions
 - Size of the structural defects (surface cracks or embedded cracks/voids)
 - Surface finish (initial crack size)
 - Geometry of the part (stress concentration)
 - Amplitude of the load cycles
 - Environment
 - Temperature
 - Chemical environment (corrosion, stress corrosion, hydrogen embrittlement, ...)

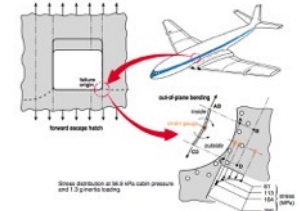


Source:

<https://commons.wikimedia.org/wiki/File:TankerSchenectady.jpg>



Source: BAE Systems



Source:

<https://aerospaceengineeringblog.com/dehavilland-comet-crash/>

Crack growth

■ Fatigue

- Critical value of K for crack growth K_c :

$$K = f(\sigma, \sqrt{a}) \geq K_c \quad [\text{MPa}\sqrt{\text{m}}]$$

K : stress intensity factor

σ : applied stress

a : characteristic size of the crack

- Crack growth (Paris equation)

$$\frac{da}{dN} = C \cdot (\Delta K)^n$$

ΔK : stress intensity factor range

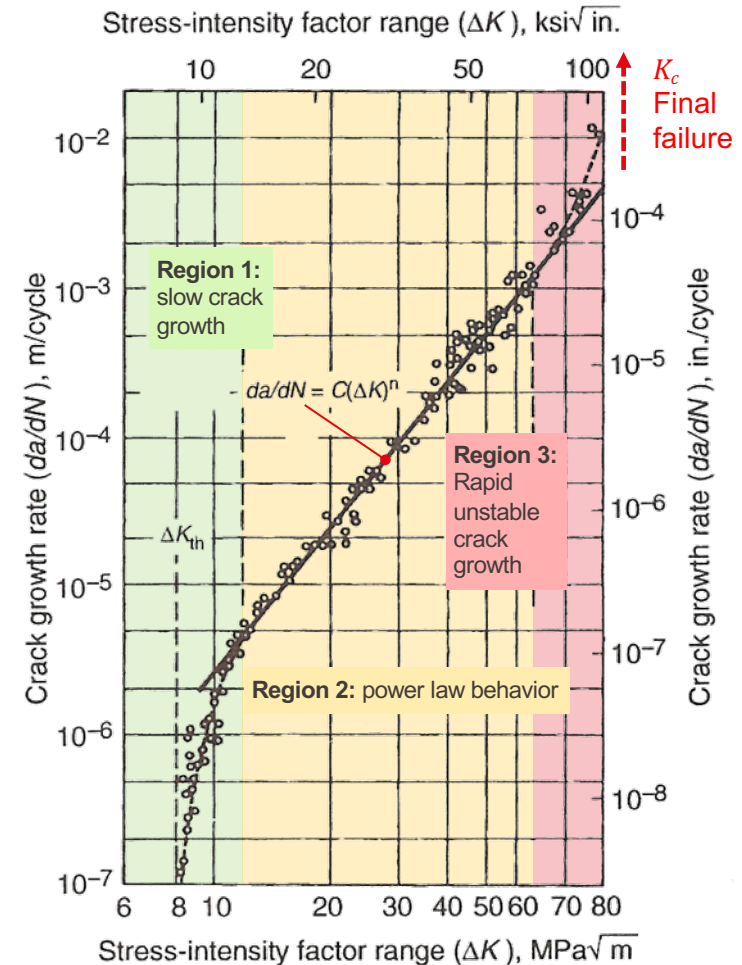
$$\Delta K = \Delta\sigma \cdot \sqrt{a \cdot f(g)} \quad [\text{MPa}\sqrt{\text{m}}]$$

C and n : constants of the material

$f(g)$: function of the specimen geometry, loading conditions, and the ratio of crack length to specimen width

$$\Delta\sigma = \sigma_{\max} - \sigma_{\min}$$

$\sigma_{\max}, \sigma_{\min}$ max, resp. min nominal stress



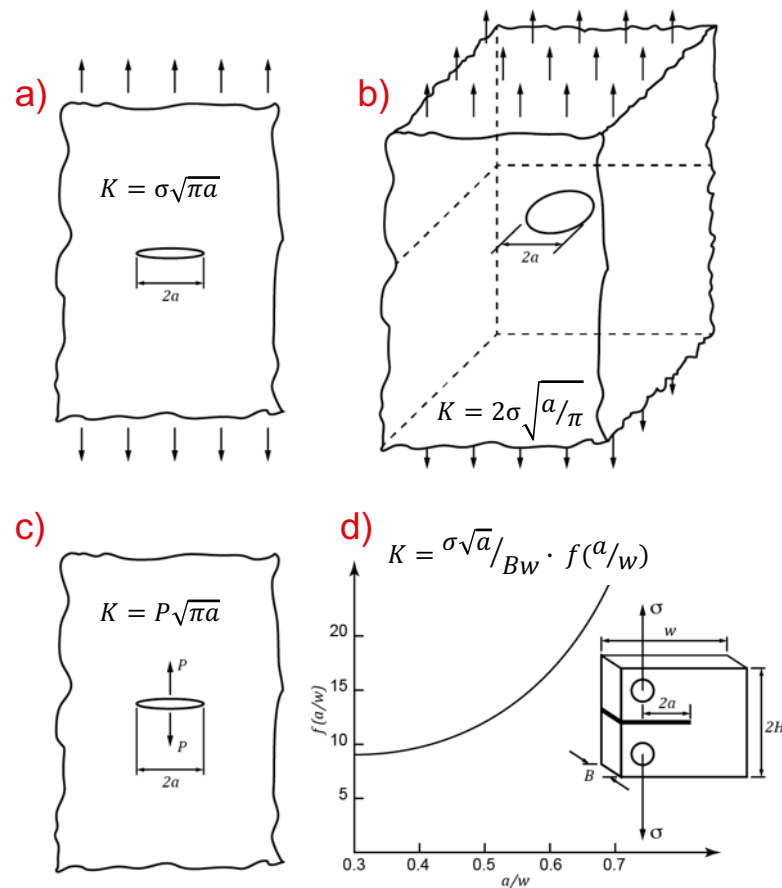
- Effect of the defect geometry the **stress-intensity factor** K :

- a) Through crack
- b) Embedded crack
- c) Crack growth through internal pressure
- d) Off-center load

Note: Geometry function f :

$$\left(\frac{da}{dN}\right)_{R,\nu} = f(\text{geometry}, a, \Delta\sigma, \text{configuration})$$

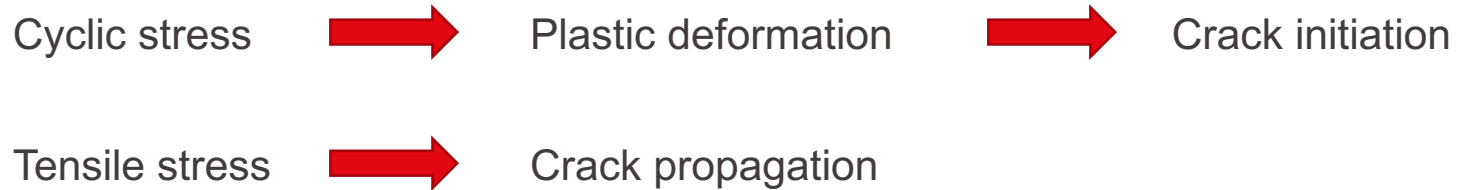
Where R : load ratio $R = \frac{\sigma_{min}}{\sigma_{max}}$
 ν : cyclic frequency



Crack growth

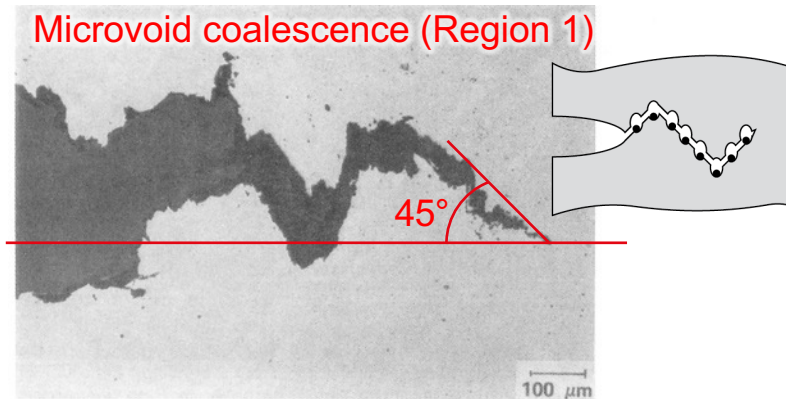
Fatigue fracture:

- Cyclic stresses
- Tensile stress
- Plastic deformation

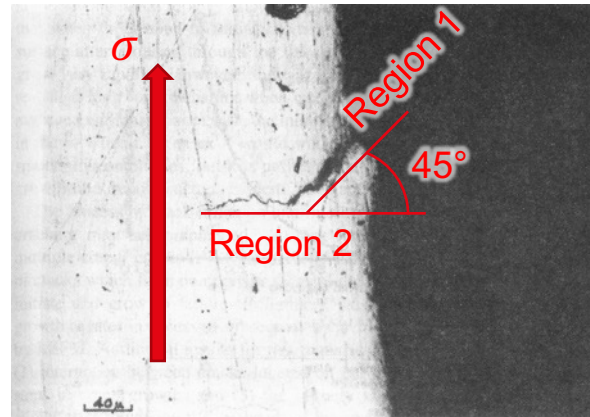


Crack growths: plastic flow and atomic plan cleavage

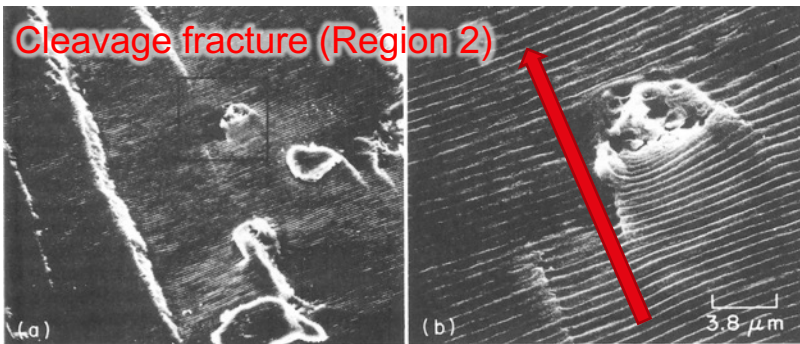
Microvoid coalescence (Region 1)



Ductile crack growth in a high-strength low-alloy steel (A 710). The zig-zag crack growth results from void initiation and growth on the plane of maximum strain

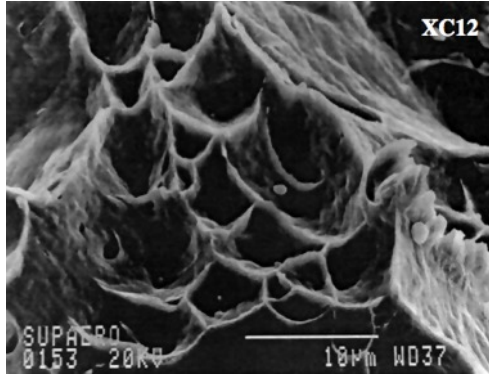


Cross section through a crack that initiates on the maximum shear plane and grows as a stage I fatigue crack until it rotates normal to the maximum tensile stress range and becomes a stage II fatigue crack

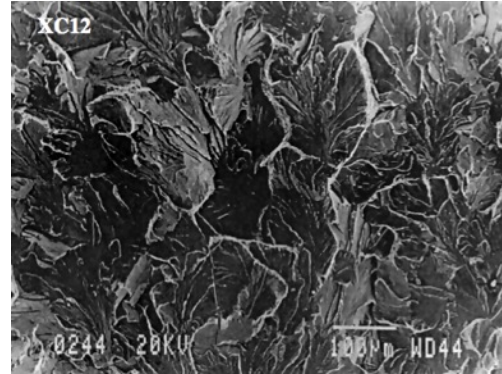


Uniformly distributed fatigue striations in an aluminum 2024-T3 alloy. (a) Tear ridge and inclusion (outlined by rectangle). (b) Higher-magnification view of the region outlined by the rectangle in (a), showing the continuity of the fracture path through and around the inclusion

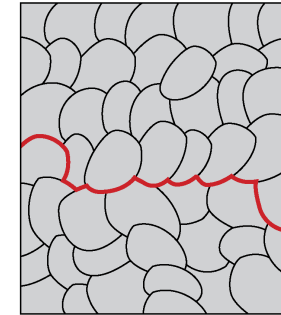
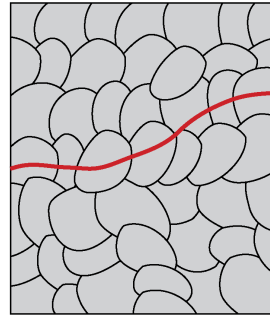
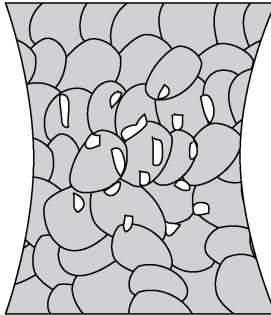
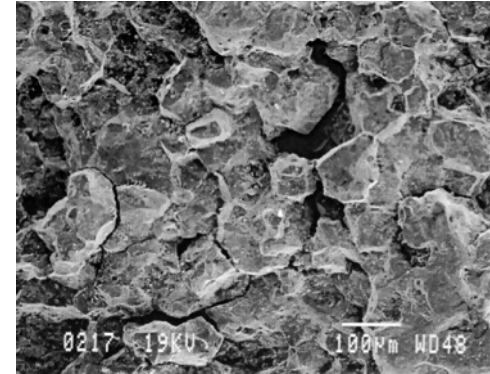
Ductile fracture
(by microvoid coalescence)



Cleavage fracture



Intergranular fracture



Mechanical Properties – Fracture Control

Space engineering - Fracture control
ECSS-E-ST-32-01C Rev. 1

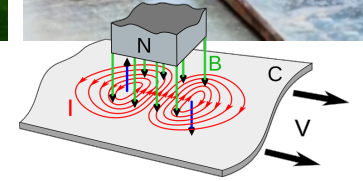
- Non Destructive Testing Methods
 - **Magnetic Particle Testing (MT)**
 - **Liquid Penetrant Testing (PT)**
 - **Radiographic Testing (RT)**
 - **Ultrasonic Testing (UT)**
 - **Electromagnetic Testing (ET)**
 - **Visual Testing (VT)**
 - Acoustic Emission Testing (AE)
 - Laser Testing Methods (LM)
 - Leak Testing (LT)
 - Magnetic Flux Leakage (MFL)
 - Neutron Radiographic Testing (NR)
 - Thermal/Infrared Testing (IR)
 - Vibration Analysis (VA)



Source: Superior Joining Technologies, Inc.



Source: N. Sakarin/Shutterstock.com



Source: Werner Sölken/wermac.org



Initial crack size detection depends on the selected NDT method
Must be taken into account when designing!

See: https://asnt.org/MajorSiteSections/About/Introduction_to_Nondestructive_Testing.aspx

Mechanical Properties: Fatigue Analysis Tools

ESA's crack growth analysis tool:

- **ESACRACK package + NASGRO package**

- <https://www.esacrack.net>
- to generate load and stress spectra from load curves associated to events
- to perform fatigue analysis. It contains fatigue materials database
- analyze fatigue crack propagation and fracture mechanics for performing assessments of structural life
- process and store fatigue crack growth properties
- analyze fatigue crack formation (initiation)
- compute stresses and stress intensity factors

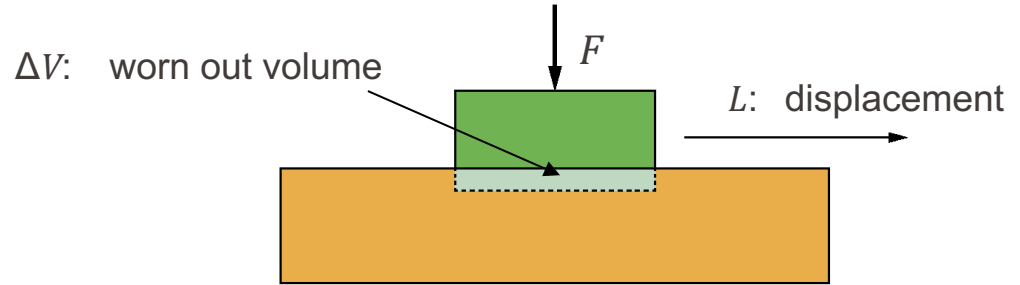
- Runs under MS Windows.

Mechanical Properties

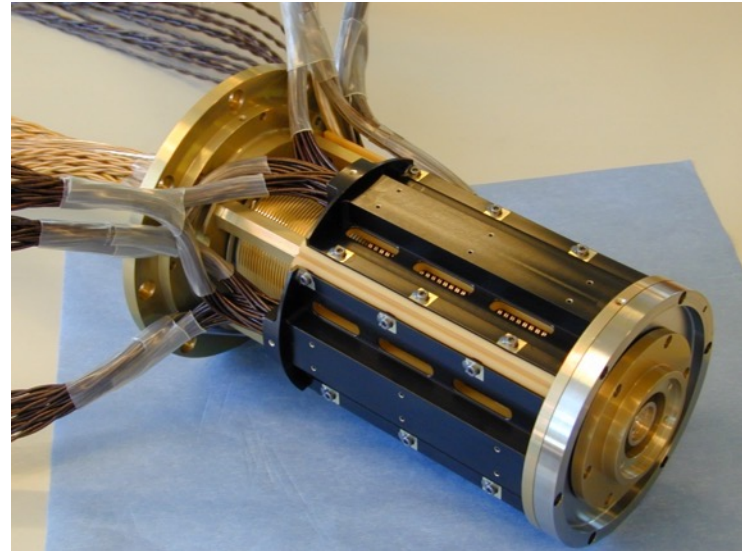
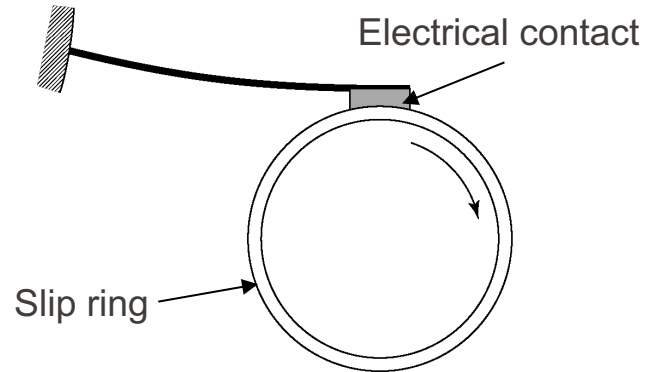
- **Wear resistance**

$$\Delta V = k \cdot F \cdot L$$

k : wear coefficient



- **Application: electrical contact**



Source: Ruag Space

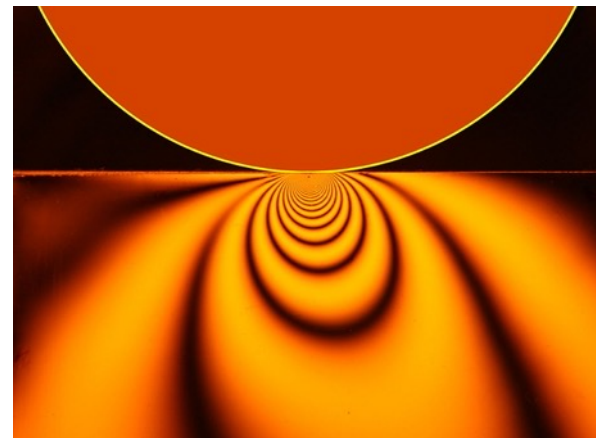
■ Wear

- Highly non-linear function of:
 - Materials in contact
 - Wear and friction coefficients: often correlated, but no simple relation between both those values
 - Chemical environment
 - Large variation of the friction in air or in vacuum
 - Example: graphite
 - Temperature
 - Speed of the friction
 - Surface roughness
 - Local pressure
-
- The local pressure is characterized through the Hertz Pressure
 - Ball bearings
 - Bolted assemblies
 - Moving parts in friction
 - Hard coating of surfaces

Mechanical Properties

- **Hertz Pressure: solids into contact**

Surfaces in contact encompass separable and sliding contacts, and bearings [ECSS-E-ST-33-01C Rev.2]

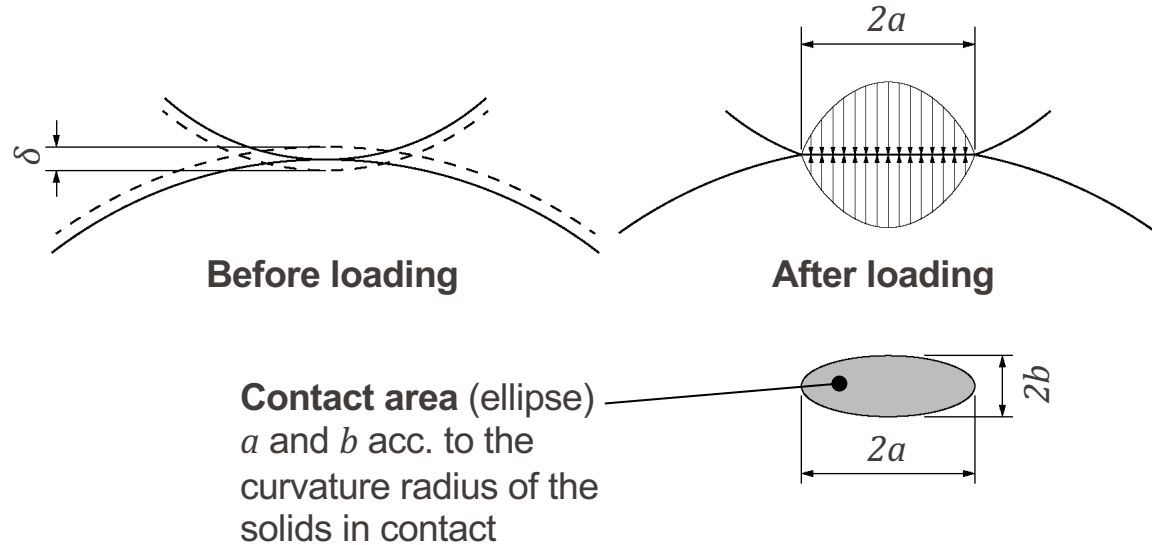
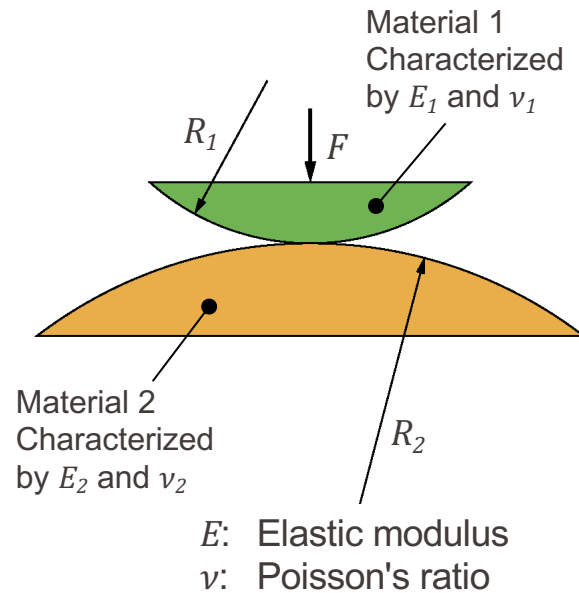


Source: Wikimedia/Reibungsphysik

- Assumptions

- The **strains are small** and within the elastic limit.
- The surfaces are **continuous and non-conforming**. This implies that the area of contact is much smaller than the characteristic dimensions of the contacting bodies.
- Each body can be considered an **elastic half-space**.
- The surfaces are **frictionless**.

■ Hertz Pressure



Hertz Pressure

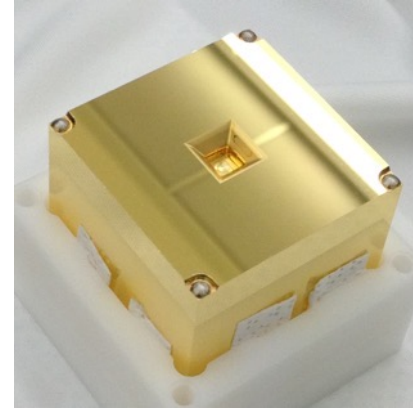
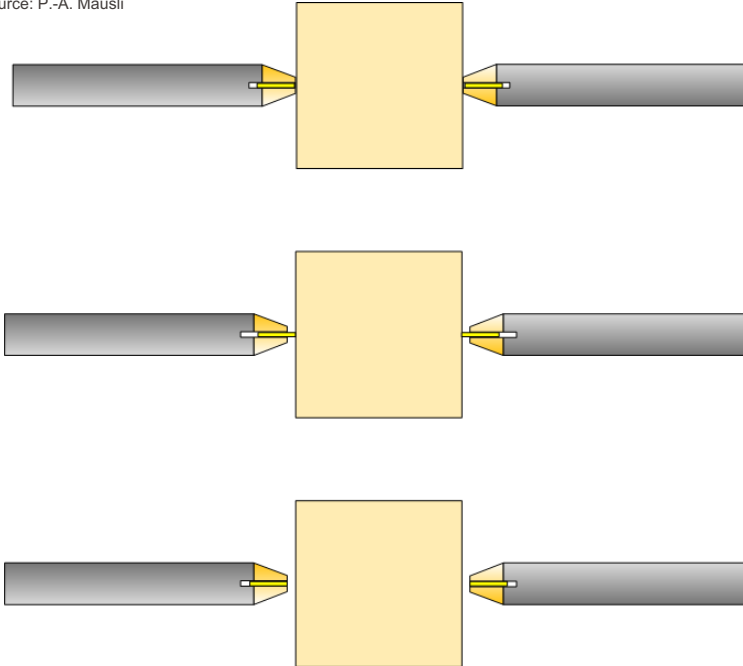
Maximum:
$$P_{H \max} = \frac{3 \cdot F}{2 \cdot \pi \cdot a \cdot b}$$

Average:
$$P_{H \text{ avg}} = \frac{2}{3} P_{H \max}$$

The size of the contact ellipse as well as of the normal approach δ of **two ellipsoids** are calculated through the Hertzian theory.

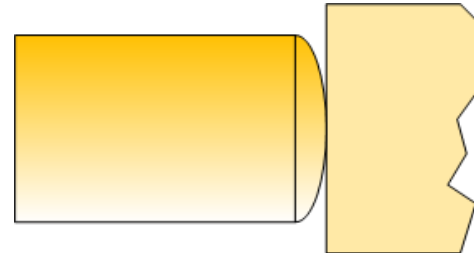
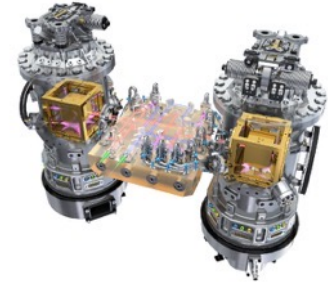
■ Grabbing, Position and Release Mechanism (GPRM) of LISA Pathfinder

Source: P.-A. Mäusli

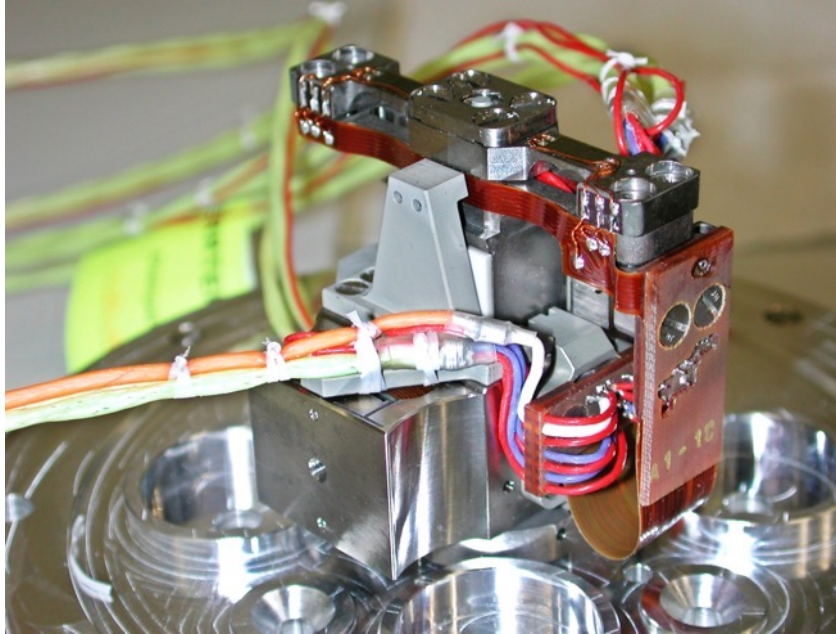


Source: CGS Spa/ESA

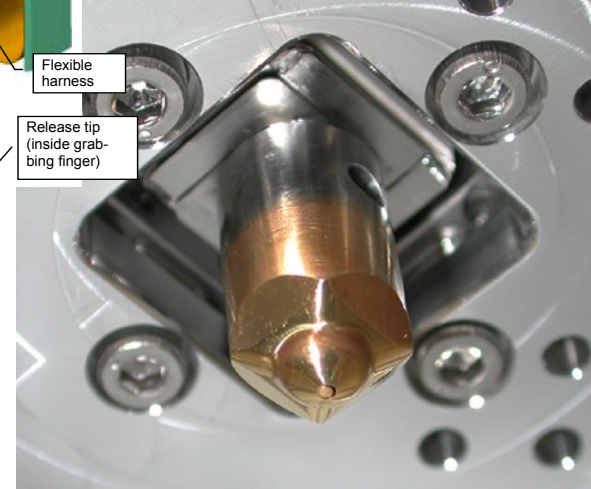
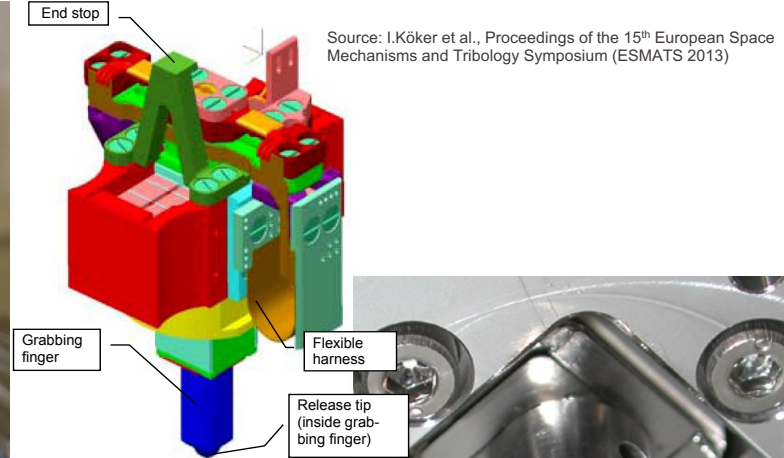
Source: ESA/ATG medialab



■ Grabbing, Position and Release Mechanism (GPRM) of LISA Pathfinder



Source: RUAG Space/P.-A. Maüsli



Source: RUAG Space/P.-A. Maüsli

Mechanical Properties - Friction

- **Friction:** the force resisting to sliding

- Friction coefficient μ :

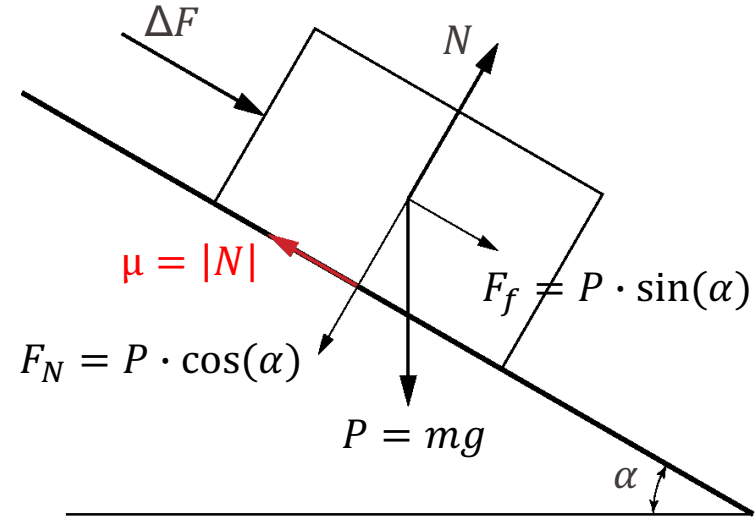
$$F_f = \mu \cdot F_N$$

- Sliding condition:

$$\mu_s = \tan(\alpha) \quad \mu_s: \text{static coefficient of friction}$$

- Types of friction

- Sliding
- Rolling
- Fretting
- Dry vs. Lubricated
- Effects of the vacuum, the temperature and the pressure: sudden change of the friction regimes



Mechanical Properties - Friction

- Usual behavior of the friction depending on:
 - Pressure (normal to the contact surface)
 - At low pressure: μ nearly constant (independent of the apparent area of contact. Friction depends only on the normal force).
 - At intermediate pressure: little increase of μ (effect of surface roughness).
 - At high pressure: rapid increase of μ that can lead to seizure (cold welding).
 - Sliding speed
 - Dry
 - At low speed: very little dependency of μ wrt speed (starting friction).
 - At intermediate speed: μ tends to decrease.
 - At high speed: possibility of jamming (increase of the contact temperature).
 - Lubricated
 - At low speed: μ is about proportional to the speed.
 - At high pressure: μ starts to decrease with the speed (kinematic regime), then increase with v^2 (dynamic regime).
 - Temperature
 - Large effect on the lubrication regimes.
 - Environment
 - Under air: highly dependent on the humidity for certain materials (e.g. graphite).

Thermal Properties

- Thermal expansion coefficient α [1/°C]
 - Key property for proper operations of space mechanisms
- Creep
 - Plastic deformation (e.g. loss of bolt preload)
 - Activated by a temperature increase
- Thermal conduction
- Specific heat
- Reflectivity, transmissivity, emissivity, absorptivity
- Phase transitions
 - Transition temperatures (liquidus, change of crystal state)
 - Stability of the phase towards temperature
 - Diffusion, segregation

Thermal Expansion

- Linear approximation

$$l(T) = l_0 \cdot (1 + \alpha(T - T_0))$$

- With

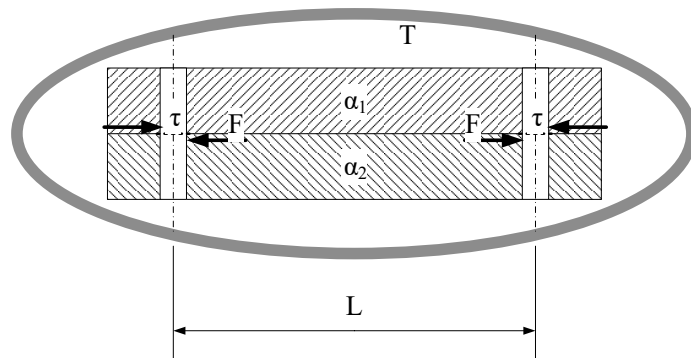
- α : thermal expansion coefficient
- $l(T)$: characteristic length of a part at temperature T
- l_0 : characteristic length (same part) at reference temperature T_0

- Bimetal effect

- Force F :

- Depends on both materials (α_1, α_2)
- Does not depend on L

\Rightarrow the shear stress depends only on the difference between both thermal expansion coefficients ($\alpha_1 - \alpha_2$)

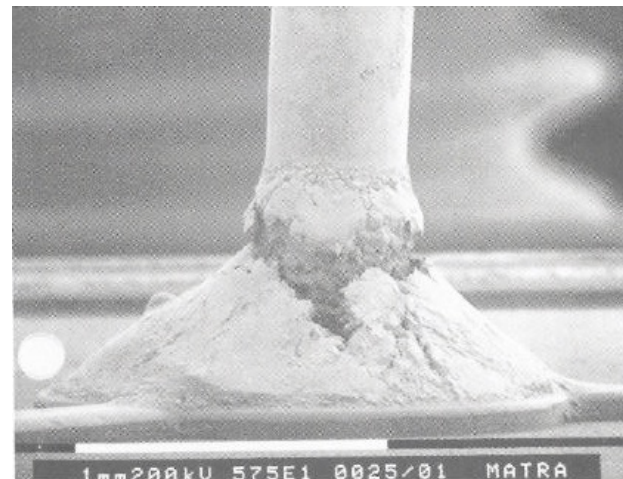
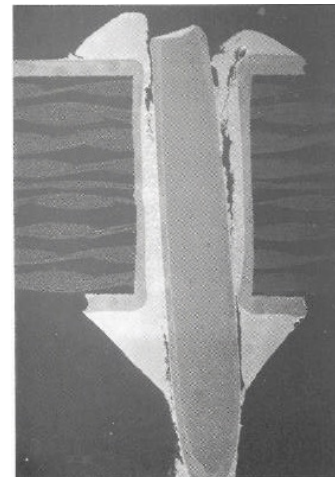


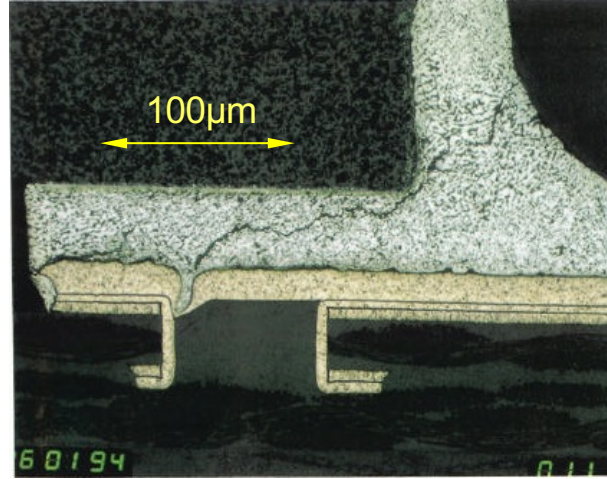
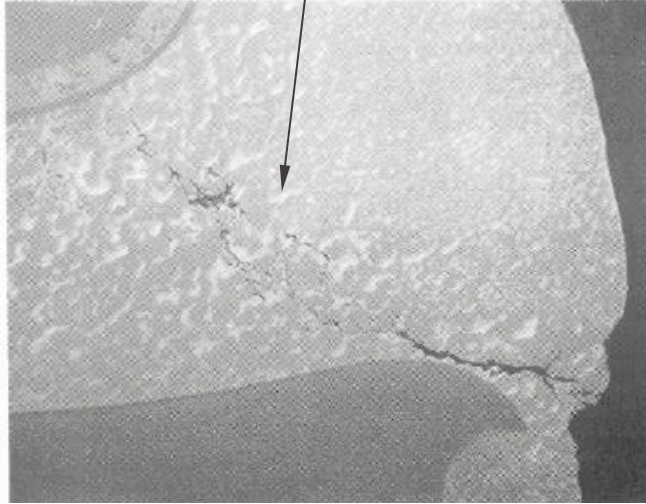
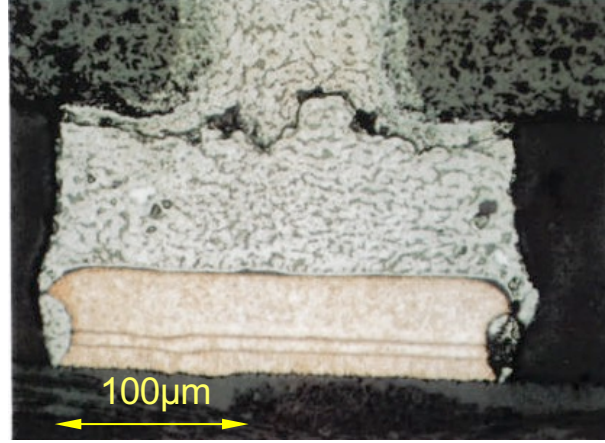
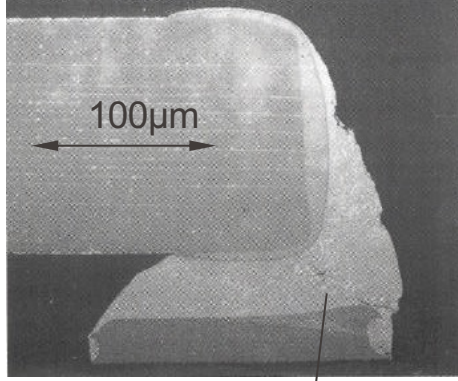
Example:

Fatigue of thermally cycled solders

- Shear stresses at the interfaces
- Combined stresses (tensile/shear) in the solder
- Differential thermal expansion of the material outside of the elastic domain
 - Fatigue
 - Initiation of crack
 - Crack growth
 - Fracture

Source: D.B. Dunn, P. Desplat, "Evaluation of conformal coatings for future spacecraft applications", ESA SP-1173, août 1994





Source: D.B. Dunn, P. Desplat, "Evaluation of conformal coatings for future spacecraft applications", ESA SP-1173, août 1994

Thermal Expansion

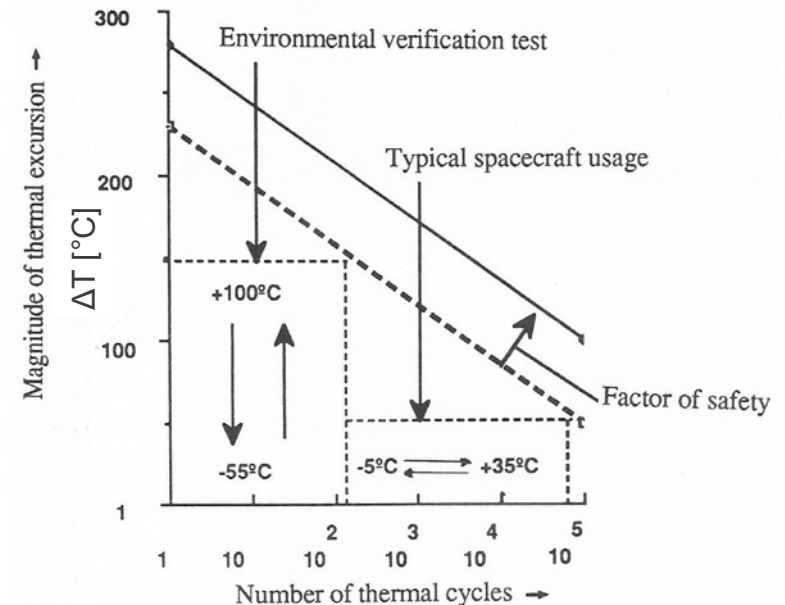
Example:

Fatigue of thermally cycled solders

- The thermal range defines the amplitude of the stresses
 - The cracks are growing after each thermal cycle
 - Qualification testing of the solder
 - Typically 200 thermal cycles
 - Temperature range: -55°C to $+100^{\circ}\text{C}$
 - Accelerated test:
 - Increase of the temperature range amplitude
- ⇒ Reduction of the number of thermal cycles

Failure data compiled by Halpin from several sources for:

- Glass-epoxy boards/10 & 12 layers
- Multiple components
- includes plated through holes, and internal connections & soldered joints



Source: J.C. Halpin, Proc. Of 31st Annual Tech. Meeting of Inst. of Environmental Science, Las Vegas, April 30-May 2, 1985, pp. 206-218

Theme 4 – Part 1 Summary

- Mechanical Properties:
 - Strength
 - Hooke's Law
 - Ultimate and Yield Strength
 - Fatigue strength
 - Stress-intensity factor
 - Three regions of crack growth
 - Crack initiation (material, size of defect, geometry, environment, loads)
 - Wear
 - Hertz Pressure
 - Friction
 - Thermomechanical effects
 - Thermal expansion
 - Fatigue

- Theme 4 – Part 2: Materials, continued
- Exercises 4.1, 4.2
- Mini Project part 1 Understanding of Technical Requirements
(cf. EE580_MP1_2025_v1 Statement.pdf)